The 2004 Indian Ocean tsunami: Tsunami source model from satellite altimetry

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Satellite altimetry measurements of sea surface heights for the first-time captured the Indian Ocean tsunami generated from the December 2004 great Sumatra earthquake. Analysis of the sea surface height profile suggests that the tsunami source, or the seafloor deformation, of the great earthquake propagated to the north at an extremely slow speed of less than 1 km/sec on average for the entire 1300-km-long segment along the northern Sumatra-Nicobar-Andaman Trench. The extremely slow propagation speed produces a very long duration of tens minutes, longer than earthquake source duration estimated (480–500 sec) from short-period *P*-wave radiation. The satellite altimetry data requires a total seismic moment of 9.86×10^{22} Nm (Mw=9.3). This estimate is approximately 2.5 times larger than the value from long-period surface wave analysis but nearly the same as that from the ultra-long-period normal mode study. The maximum amount of slip (~30 m) is identified in an offshore region closest to the northern most part of Sumatra where the largest tsunami run-up heights were observed. **Key words:** 2004 Sumatra earthquake, tsunami, source model, satellite, Indian Ocean.

1. Introduction

A great earthquake occurred northwest of Sumatra at 0:59 UTC, December 26, 2004. USGS/NEIC (United States Geological Survey/National Earthquake Information Center) and Harvard University assigned a moment-magnitude (Mw) of 9.0 to this earthquake. Soon afterwards an analysis of the longest period normal mode yielded a seismic moment of 1.0×10^{23} Nm and revised the moment-magnitude as Mw 9.3 (Stein and Okal, 2005).

The earthquake generated a devastating tsunami throughout the Indian Ocean. Assuming that the one-day aftershock distribution is representative of the earthquake rupture zone, the total length is approximately 1400 km along the northern Sumatra-Nicobar-Andaman trench (Fig. 1). The tsunami travel times at tide gauge stations around the Indian Ocean, however, suggested that the tsunami source area was confined with the southern 600 to 800 km zone (Lay *et al.*, 2005).

The maximum tsunami height of 13–49 m was observed on the west coast of Banda Aceh, Sumatra (International Tsunami Survey Team, 2005; Tsunami Field Survey Team in Banda Aceh of Indonesia, 2005) whereas tsunami heights were 1–7 m at the Nicobar and Andaman Islands (Department of Ocean Development, 2005). The observed distribution of tsunami heights may be related to a possible heterogeneity of the tsunami excitation strength along the trench.

Two hours after the occurrence of the great earthquake, two NASA/French Space Agency's joint mission satellites "Jason-1" and "TOPEX/Poseidon" passed across the Indian Ocean and measured sea surface height (SSH) disturbed by the Indian Ocean tsunami from the great Sumatra earthquake (Fig. 1(a)) (Gower, 2005). Previous modeling explained the observed satellite SSH data successfully (Titov, 2005) except for a region between 0° N and 15°N in the Jason-1 observations. Lay *et al.* (2005) suggested that a slow slip is required for the SSH observation between 5° N and 14°N. In this study, we analyze the SSH data from the two satellites to investigate heterogeneous source model of the Indian Ocean tsunami.

2. Sea Surface Heights observed from Satellites

Satellites "Jason-1" and "TOPEX/Poseidon" passed across the Indian Ocean from southwest to northeast at a speed of approximately 7 km/sec (Fig. 1(a)). The accuracy of satellite altimetry is less than 5 cm and its spatial resolution is approximately 15 minutes of the arc (\sim 27 km) (JPL/NASA, 2005).

Original SSH data are processed routinely to remove contributions of geoid, ocean tide, atmospheric pressure, and vapor in atmosphere. The remaining SSH data include oceanographic effects. The spatial distribution of the Indian Ocean tsunami two hours after the earthquake can be defined by SSH differences between successive cycles of satellite altimetry. For Jason-1, it is calculated from cycles 109 (passed the Equator at 02:55:24 UTC, 26 Decem-

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Fig. 1. (a) Ground tracks of satellite altimetry with Jason-1 and TOPEX/Poseidon (thin lines). Two satellites passed across the Indian Ocean two hours after the occurrence of the great Sumatra earthquake (Gower, 2005; JPL/NASA, 2005). Closed circles on the ground tracks indicate the points that sea surface height (SSH) difference from two successive cycles before and after the great Sumatra earthquake can be defined. The epicenters of mainshock and aftershocks two hours after the great event are also shown. (b) Subfault setting for the inversion in this study. We model the entire aftershock zone, with a length of 1400 km along the northern Sumatra-Nicobar-Andaman trench, using 14 subfaults placed parallel to the trench (E1–E14). O₁ to O₄ (triangles) indicate possible rupture initiation points. Aftershock distribution, including the mainshock epicenter, within 1 day after the occurrence of the mainshock is also shown.



Fig. 2. (a) Observed sea surface height (SSH) by satellite altimetry from Jason-1 and TOPEX/Poseidon measurements. Gray and green dots indicate observed SSH data in cycles 108 and 109, respectively, from Jason-1 (upper panel) and those in cycles 451 and 452, respectively, from TOPEX/Poseidon (lower panel). The Indian Ocean tsunami from the great Sumatra earthquake can be defined by taking the difference between successive cycle pairs (Red circles). Blue circles depict the best-fit synthetic SSH computed from an extremely slow propagation model with its velocity of 0.7 km/sec. (b) Comparison of synthetic SSH distribution with observed one (red circles). Green and blue circles show the synthetics from the fast propagation models with velocities of 3.0 km/sec and 2.5 km/sec, respectively. Gray circles show the synthetics from the fast propagation models with velocity of 2.5 km/sec but whose source area is limited in southern 700 km-long segment.

Subfault #	Length	Width	Longitude ¹	Latitude ¹	Depth ¹	Strike	Dip	Rake	Amount of slip	Mo^2	Mw_sub
	[km]	[km]			[km]	[°]	[°]	[°]		[m]	[Nm]
E14	100	150	92.01	13.51	10	25	10	130	0.0 ± 4.3	0.00E+00	_
E13	100	150	91.78	12.51	10	15	10	120	27.2 ± 3.6	1.43E+22	8.70
E12	100	150	91.63	11.56	10	10	10	115	25.7 ± 2.2	1.35E+22	8.69
E11	100	150	91.48	10.66	10	10	10	115	6.1 ± 1.6	3.20E+21	8.27
E10	100	150	91.51	9.60	10	0	10	106	12.0 ± 1.5	6.30E+21	8.47
E9	100	150	91.64	8.60	10	350	10	99	1.5 ± 2.3	7.93E+20	7.87
E8	100	150	92.08	7.64	10	335	10	86	11.5 ± 2.3	6.04E+21	8.45
E7	100	150	92.53	6.78	10	330	10	90	9.4 ± 2.5	4.96E+21	8.40
E6	100	150	92.63	6.12	10	350	10	100	23.4 ± 2.2	1.23E+22	8.66
E5	100	150	92.88	5.18	10	345	10	102	10.4 ± 2.2	5.46E+21	8.42
E4	100	150	93.16	4.15	10	340	10	105	29.1 ± 2.1	1.53E+22	8.72
E3	100	150	93.64	3.33	10	330	10	104	14.9 ± 2.6	7.82E+21	8.53
E2	100	150	94.50	2.57	10	310	10	91	0.0 ± 3.0	0.00E + 00	_
E1	100	150	95.54	2.13	10	290	10	71	16.5 ± 2.2	8.66E+21	8.56
									total Mo =	9.86E + 22	9.26

Table 1. Subfault Parameters and Estimated Parameters from the Inversion.

¹Values at the east corner of the upper edge in each subfault.

²Rigidty is assumed to be 3.5×10^{10} N/m².

ber 2004) and 108 (04:56:52 UTC, 16 December 2004) on pass 129. For TOPEX/Poseidon, it is calculated from cycles 452 (03:01:57 UTC, 26 December 2004) and 451 (05:03:25 UTC, 16 December 2004) on pass 129. The observed SSH differences from Jason-1 and TOPEX/Poseidon show considerable water surface disturbance due to the Indian Ocean tsunami along the satellite tracks (Fig. 2(a)), although both include data gaps in each cycle pairs. Total number of observed SSH differences thus defined is 344 and 155 for Jason-1 and TOPEX/Poseidon, respectively.

3. Inversion

We invert the satellite SSH difference data to estimate the tsunami source model, including the effects of tsunami source propagation. Propagating tsunami source is expressed by a set of vertically displaced seafloor with different onset time. We relate each vertically displaced seafloor to slip on subfaults. Figure 1(b) shows the prescribed fault model, consisting of 14 subfaults with a trench-parallellength of 100 km. A study of coral growth and GPS measurements in the Sumatra forearc indicated that the interseismic locked zone on subduction interface does not extend farther landward than the Mentawai Island chain west of the Sumatra (Simoes *et al.*, 2004). We therefore set the down-dip width of subfaults to be 150 km.

Global seismic networks poorly controlled depth of aftershocks following the Sumatra earthquake. Araki *et al.* (2005) suggested from ocean-bottom seismographic observation that average dip angle of the aftershock distribution is 8° to 12° in the outer-arc high west of northern Sumatra. We therefore assume that dip angle for each of the subfaults is 10° . The dip angle is nearly the same as that of the Harvard Centroid Moment Tensor (CMT) solution of the mainshock, and consistent with a possible plate interface based on an accurate hypocenter catalog (Engdahl *et al.*, 1998).

Slip angle on each subfault is estimated from the prin-



Fig. 3. Normalized variance variation with respect to rupture velocity in the inversion. We assumed four possible rupture start points, O_1 to O_4 , as shown in Fig. 1(b). Normalized variance is defined by the root-mean-squares of difference between observed SSH difference and synthetic one, divided by the root-mean-squares of observed SSH difference.

cipal stress axis of aftershocks for the first 10 days. We selected only thrust events from the Harvard CMT catalog and assumed that the average compressional-axis directions are parallel to the slip direction on each subfault. Vertical displacement of seafloor is calculated by Okada's formula (Okada, 1985). Subfault parameters are listed in Table 1.

We compute tsunami wavefield on a spherical coordinate system from each subfault by numerically solving the shallow water (long-wave) equations using a finite difference method (Satake, 1995). The computation region is shown



Fig. 4. Model seafloor deformation patterns calculated from best-fit source models with various widths (w) and dip angles (δ) of subfaults. Average propagation velocity (Vr) that produces minimum variance in prescribed width and dip angle pair is shown within each panel.

in Fig. 1(a). We set the grid size of the computation as 3 minute of arc (\sim 5 km), small enough to represent minimum wavelength (\sim 200 km) of the Indian Ocean tsunami observed with two satellites. The grid data are made from ETOPO2 (Smith and Sandwell, 1997). The computation is made at every 5 sec, satisfying the stability condition of finite difference computation. By using satellite orbital information (latitude, longitude, and time) and *a priori* propagation velocity (*Vr*), we then construct satellite pass-segment

Greens functions to use them in the linear inversion. We apply a linear inversion scheme with a non-negative constraint to solve this inversion problem. A rise time, 150 sec, of seafloor deformation is used because it produces minimum variance.

4. Results

Since the epicenter of offshore earthquake is, in general, poorly located, we first examine the rupture initiation point.

We assume four rupture starting points: O_1 , O_2 , O_3 , and O_4 as shown in Fig. 1(b). Point O_1 is located on the southeast edge of subfault E1 and consistent with USGS/NEIC epicenter. Point O_2 is 50 km from O_1 along the trench, O_3 is 50 km from O_2 , and O_4 is set at the center of subfault E2.

Figure 3 shows normalized variances as a function of average propagation velocity (Vr) and suggests that the tsunami source propagated from O₁ unilaterally to NNE, although difference in the normalized variance is small. A minimum normalized variance of 0.281 is obtained at propagation velocity of Vr = 0.7 km/sec. Such a slow propagation feature is less affected by assumed dip angle and fault width: in the cases of different values in subfault dip angle and width, overall seafloor deformation pattern is not changed largely and the best-fit propagation velocity is always between 0.7 km/sec and 0.8 km/sec (Fig. 4). The best-fit solutions suggest that the tsunami source did not reach near northernmost subfault E14. Thus, the entire fault length measured parallel to the concaved trench axis is 1300 km. The extremely slow propagation model reproduces a fairly good synthetic SSH distribution (Fig. 2(a)) whereas fast propagation models with velocity of a few km/sec do not explain the observed trough with wide south-facing slope between 6°N and 19°N in Jason-1 data (Fig. 2(b)). Lay et al. (2005) explained the Jason-1 SSH data by introducing a combination of a fast rupture (Vr = 2 km/s, rise time=50 s) in the southern 745 km segment and a slow rupture (Vr = 0.75 km/s, rise time=3500 s) in the northern segment. Slow propagation estimated by the present study may correspond to the slow rupture component of Lay et al. (2005), although it is difficult to compare our result with theirs, because we do not vary propagation velocity and rise time during the tsunami source propagation.

It is also worth noting that instantaneous propagation models (i.e., $Vr = \infty$ km/sec) that are traditionally used in tsunami modeling yield minimum variances much larger than the 1300 km-long tsunami source propagating model; minimum normalized variances for instantaneous propagation models on the southern 700 km, 900 km, 1200 km, and 1300 km segments are 0.604, 0.503, 0.461, and 0.421, respectively. Previously estimated tsunami source of 600 to 800 km-long seems to be underestimated due to the traditional assumption of instantaneous tsunami excitation over entire tsunami source area. The best solution for Vr = 0.7 km/sec is listed in Table 1.

5. Discussions and Conclusion

The northern extent and propagation velocity of the tsunami source can also be examined by tsunami travel times at northern tide gauge stations. Paradip and Vishakhapatnam are two northernmost stations (Fig. 1(a)). The observed travel times at both stations are 156 minutes (Department of Ocean Development, 2005). To estimate the source extent from the tsunami travel time, we have to correct for the rupture propagation with a finite velocity. Corrected travel times Tc = T - Tp are simply estimated by subtracting Tp = L/Vr from observed travel times T, where L is the along-trench distance between the epicenter and effective tsunami generation point which can be thought to be "nearest (in tsunami diffraction diagram)" to a tide

gauge station. L always equals to length (Ls) of the tsunami source and is the same for Paradip and Vishakhapatnam except for $Ls \ge 1300$ km. For $Ls \ge 1300$ km, L equals to Ls for Paradip but not for Vishakhapatnam; graphical inspection of tsunami diffraction diagram shows that subfault E13 is slightly nearer to Vishakhapatnam than subfault E14. For Vishakhapatnam, therefore, we fix L = 1250 km, which is the distance from the epicenter to the center of subfault E13.

Tsunami source should be outlined by back-projecting tsunami wavefronts (black curves in Fig. 5) if shallow bathymetry of ETOPO2, location of tide gauge on bathymetric grid, and tide gauge clocks are all accurate, and subfault geometry is appropriate. Since we cannot exclude these error factors, we introduce allowable range of ± 10 min in corrected travel times. If outline of a tsunami source is included in both of the allowable ranges (blue curves for Paradip and red curves for Vishakhapatnam in Fig. 5), the tsunami source is considered acceptable.

Figure 5(a) suggests that slow propagating source models with velocities from 0.6 km/sec to 1.0 km/sec are acceptable for $Ls \ge 1300$ km. Propagation velocities from 0.7 km/sec to 0.9 km/sec are acceptable if allowable range is set ± 5 min whereas those from 0.5 km/sec to 1.5 km/sec are acceptable if allowable range is set ± 15 min.

Figure 5(b) suggests that no acceptable solution is obtained in velocity interval from 0.5 km/sec to 3.0 km/sec for 700 km-long tsunami source models (Ls = 700 km) when allowable range is set ± 10 min No acceptable solution is obtained in the same velocity interval when allowable range is set ± 5 min or ± 15 min. Long tsunami source with slow propagating velocity, therefore, seems to be a probable solution.

Average propagation velocity of the tsunami source was estimated from the inversion to be an extremely slow Vr = 0.7 km/sec or so. Total source duration is, therefore, roughly estimated to be 1300 km/0.7 km/sec=1900 sec or 30 minutes, approximately four times longer than source duration estimates (480–500 sec) from short-period *P*-waves (Ishii *et al.*, 2005; Ni *et al.*, 2005; Kruger and Ohrnberger, 2005). When average propagation velocity is 0.6 km/sec or 1.0 km/sec, total source duration becomes 1400 km/0.6 km/sec=2300 sec (~40 min) or 1300 km/1.0 km/sec=1300 sec (~20 min).

The large amount of slip, which produces the large seafloor deformation, is identified on subfault E4 closest to west coast of the northern Sumatra when longer tsunami source models with slow propagation are concerned. The strong local tsunami source is probably responsible to the observed large tsunami height of approximately 35 m or 49 m at west coast of northern Sumatra (International Tsunami Survey Team, 2005; Tsunami Field Survey Team in Banda Aceh of Indonesia, 2005). Slip distribution estimated from seismic wave studies (Ji, 2005; Taymaz *et al.*, 2005; Yagi, 2005; Yamanaka, 2005) also suggested large asperity in the almost same region.

Although the inversion suggests that large amount of slip was occurred on subfaults E12 and E13, a close examination of satellite pass-segment Green functions implies that subfault E13 may not be well constrained if Vr is 0.7



Fig. 5. Comparison of various tsunami source models (model seafloor deformation patterns calculated from best-fit source models inverted from SSH data) with corrected tsunami travel times at the northernmost tide gauge stations, Paradip and Vishakhapatnam. Black curves indicate imaginary back-projecting tsunami wavefront with the corrected travel times (see the text) calculated based on ETOPO2 bathymetry. Blue and red curves sandwiching the black curves represent the allowable range (± 10 min) of corrected travel times for Paradip and Vishakhapatnam, respectively. Average propagation velocity Vr is shown in the bottom of each panel. (a) Comparison between corrected travel times and long tsunami sources estimated when 1400 km-long segment is allowed to generate tsunami. (b) Comparison between corrected travel times and short tsunami sources estimated when tsunami source is limited in southern 700 km-long segment.

km/sec because the southward-traveling leading wave crest from E13 coincidentally falls in one of the Jason-1 data gaps between 5°N and 6°N. Since third largest amount of slip on subfault E12 is well constrained from the observed SSH data, the tsunami source had to propagate at least 1200 km to the north from the epicenter along the trench. Tsunami source models that are confined in the 700 km-long Sumatra and Nicobar segments cannot explain observed wide trough between 6°N and 19°N in Jason-1 data (Fig. 2(b)). Large amount of slip near Andaman Island, however, may not be explained smaller tsunami heights of 1–5 m in the Andaman Islands (Department of Ocean Development, 2005). Slow seafloor deformation (long rise time) in this region may be required.

Our inversion result suggests total seismic moment $Mo = 9.86 \times 10^{22}$ Nm (Mw=9.3) (Table 1). This estimate is 2.5 times larger than the previous estimate by USGS/NEIC and Harvard CMT but nearly the same as that of the longest period normal mode study (Stein and Okal, 2005). The average dislocation is approximately 14 m along the entire 1300 km-long fault.

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